

Fundamentals of Astrodynamics and Applications 4th Ed

Consolidated Errata

July 12, 2017

This listing is an on-going document of corrections and clarifications encountered in the book. I appreciate any comments and questions you find. I use RHS for “right hand side” when referring to equations and N/A for not applicable. You may reach me at: dvallado@agi.com or davallado@gmail.com. Changes in equations are sometimes indicated by circles. I have tried to indicate changes that were present in previous editions as I know many of you have those copies. For many corrections in the 2nd edition, the first and second printings had identical pages, unless otherwise noted with the first printing pages being in parentheses. The exact description may differ, but it should get you close enough.

Page xiv, Algorithm 1: The cross reference should say pg 63, not 71.

Page 107, Fig 2-19: (3rd pg 115, 2nd pg 115, 1st pg 142) The units for Mean motion should be (rev/day²/2) and for Mean motion second derivative (rev/day³/6). The Mean motion second derivative should have a negative sign in the box before the 0 exponent. The superscripted values were missing. The checksum for the first line should be 9 and the check sum for the second line should be 6.

Page 110, 2nd equation: (3rd pg 118) The velocity equation should be

$$v \begin{bmatrix} -\cos(\alpha) \sin(\delta) \cos(\beta) \cos(\phi_{fpav}) - \sin(\alpha) \sin(\beta) \cos(\phi_{fpav}) + \cos(\alpha) \cos(\delta) \sin(\phi_{fpav}) \\ -\sin(\alpha) \sin(\delta) \cos(\beta) \sin(\phi_{fpav}) + \cos(\alpha) \sin(\beta) \cos(\phi_{fpav}) + \sin(\alpha) \cos(\delta) \sin(\phi_{fpav}) \\ \cos(\alpha) \cos(\delta) \cos(\phi_{fpav}) + \sin(\delta) \cos(\phi_{fpav}) \end{bmatrix}$$

Page 120, Position and velocity vectors: (3rd pg 127-128, 2nd pg 126) the last 2 decimal places of the position and velocity vector components should be 68, 32, 19 and 79, 40, and 10.

Page 158, First paragraph: (3rd pg 166, 2nd pg 163, 1st pg 44) It should be just “clockwise”.

Page 173, Algorithm 13: (3rd pg 180, 2nd pg 178) The equation for b should be corrected as follows:

$$b = R_{\oplus} \sqrt{(1 - e_b^2)} \text{SIGN}(r_K) = r_b$$

Page 193, Eq 3-52: (3rd pg 199) The last term should be “-” instead of “+” (TDB₀).

Page 208, Fig 3-26: The IAU 1976 precession matrix elements should be reversed and of opposite sign.

Page 213, Last para: (3rd pg 219, 2nd pg 212) The summation should go from 0 - 4, not 0 - 5.

Page 216, Eq 3-67: (3rd pg 221) The constant should be -0.000 029 956T⁴.

Page 225, Eq 3-82: (3rd pg 230, 2nd pg 210, 1st correct) The equations actually were from 1996 values and are thus a little different. They should be as follows:

$$\begin{aligned}
M_{\odot} &= 134.962\ 981\ 39^{\circ} + (1325r + 198.867\ 398\ 1)T_{TT} + 0.008\ 697\ 2T_{TT}^2 + 1.78 \times 10^{-5}T_{TT}^3 \\
M_{\ominus} &= 357.527\ 723\ 33^{\circ} + (99r + 359.050\ 340\ 0)T_{TT} - 0.000\ 160\ 3T_{TT}^2 - 3.3 \times 10^{-6}T_{TT}^3 \\
u_{M_{\odot}} &= 93.271\ 910\ 28^{\circ} + (1342r + 82.017\ 538\ 1)T_{TT} - 0.003\ 682\ 5T_{TT}^2 + 3.1 \times 10^{-6}T_{TT}^3 \\
D_{\odot} &= 297.850\ 363\ 06^{\circ} + (1236r + 307.111\ 480\ 0)T_{TT} - 0.001\ 914\ 2T_{TT}^2 + 5.3 \times 10^{-6}T_{TT}^3 \\
\Omega_{\odot} &= 125.044\ 522\ 22^{\circ} - (5r + 134.136\ 260\ 8)T_{TT} + 0.002\ 070\ 8T_{TT}^2 + 2.2 \times 10^{-6}T_{TT}^3
\end{aligned}$$

Page 226, Sentence after Eq 3-86: The end should say “the equation after Eq. (3-72)”.

Page 232, Text of table 3-6: The velocity units should be “m/s”, not “mm/s”.

Page 277-281, Sun algorithm: (3rd pg 279-283, 2nd pg 265-269 (263-267), 1st 181-184) The equations should be made identical to the Almanac version, which is TOD, not MOD. The development shows where the equations come from, but the accuracy is slightly better using the truncated terms from the Almanac. It changes the example problem slightly, and this is evident in the Matlab approach which has been updated.

Page 284, first paragraph of text after the example: (3rd pg 287, 2nd pg 273 (271)) The “and 3000 m in altitude” can be deleted because it is not needed for the problem.

Page 288-289, Eq for magnitude of the Moon: (3rd pg 290-291, 2nd pg 276-277 (274-275), 1st 187-188) The numerator should be $R_{\oplus \odot}$, not “1”.

Page 298, Example 5-5: (3rd pg 300, 2nd pg 286 (284), 1st 190-192) The “TU’s” should be replaced by “day”. This causes several calculations to be different.

$$\begin{aligned}
\dot{r}_{XYZ} &= -4.075\ 931\ \hat{X} - 3.578\ 308\ \hat{Y} + 0.105\ 970\ \hat{Z}\ \text{AU} \\
\dot{r}_{XYZ(J2000)}, \dot{v}_{XYZ(J2000)} &= \mathbf{ROT1}(-\epsilon) \dot{r}_{XYZ} \dot{v}_{XYZ} \\
\dot{r}_{XYZ(J2000)} &= -4.075\ 931\ \hat{I} - 3.325\ 169\ \hat{J} - 1.326\ 186\ \hat{K}\ \text{AU} \\
&= -609,750,543\ \hat{I} - 497,438,245\ \hat{J} - 198,394,607\ \hat{K}\ \text{km} \\
\dot{v}_{XYZ(J2000)} &= 0.004\ 889\ \hat{I} - 0.004\ 846\ \hat{J} - 0.002\ 197\ \hat{K}\ \text{AU/day} \\
&= 8.46560\ \hat{I} - 8.39137\ \hat{J} - 3.80323\ \hat{K}\ \text{km/s}
\end{aligned}$$

Page 299, Last Eq: (3rd pg 301, 2nd pg 287 (285)) The umbra and penumbra equations should not have the “=” sign before the answer in degrees.

Page 362-364, Eq 6-38, Algorithm 44, and Ex 6-8 and Ex 6-9: (3rd pg 363-366, 2nd pg 348-352 (346-350), 1st 318-321) The equation should be $\vartheta = \pi - \alpha_L$ in each. In Ex 6-8, the target is “in front of” the interceptor, $\omega_{tgt} = 0.000\ 438\ \text{rad/s}$, the phasing value is “smaller” than the original orbit, and the interceptor enters a “lower” orbit. In Ex 6-9, the target is “in front of” the interceptor, $\omega_{tgt} = 0.000\ 072\ 9\ \text{rad/s}$, $\omega_{int} = 0.000\ 438\ \text{rad/s}$, and the target satellite begins “in front of” the interceptor.

Page 369, Ex 6-10: (3rd pg 371, 2nd pg 357 (355), 1st 326) $\omega_{tgt} = 0.000\ 072\ 9\ \text{rad/s}$, and $\omega_{int} = 0.001\ 045\ 7\ \text{rad/s}$,

Page 386, Eq 6-55: (3rd pg 388, 2nd pg 373 (371), 1st 342) The two summations should be divided, not multiplied.

Page 388, Ex 6-13 v_{acc} equation: (3rd pg 388, 2nd pg 374 (372)) The v_{acc} equation should be $0.75\ (6578.136) / (845.0472)$. (remove the “1/”)

Page 414-416, Alg 49 and 50 (3rd pg 412-416, 2nd pg 397-399(395-397), 1st pg 366-368) There have been several updates to match the final form given in Vallado and Alfano. 2014. Curvilinear Coordinate

Transformation for Relative Motion. 118 (3):253-271, *Celestial Mechanics and Dynamical Astronomy* and the few errata in (2016) 125:263–264.

Page 445, 2nd Eq after ELSE: (3rd pg 441, 2nd pg 425 (423), 1st 399) The denominator should be changed as follows:

$$e \sin(\nu_2) = \frac{\cos(\Delta\nu_{32})e \cos(\nu_2) - e \cos(\nu_3)}{\sin(\Delta\nu_{32})}$$

Page 473, 475, After 2nd para, and in Alg 56: (3rd pg 471, 2nd pg 454 (452), 1st 428) Add the following para and equation:

To find the minimum time with a_{min} new values of α_e and β_e are required. Prussing and Conway (1992, 72) show the result.

$$\alpha_{min} = \pi \quad \sin\left(\frac{\beta_{min}}{2}\right) = \sqrt{\frac{s-c}{s}}$$

Change the α_e and β_e subscripts to “min” in Alg. 56.

Page 489, 3rd full para (3rd pg 486, 2nd pg 461(460), 1st pg 436) The reference is for pgs 231-236, not 193-198.

Page 496, Alg 59: (3rd pg 493, 2nd pg 468 (466), 1st 443) If $a > 0.0$, calculate the minimum values first, then find the subscripted e values.

$$\alpha_{min} = \pi \quad \sin\left(\frac{\beta_{min}}{2}\right) = \sqrt{\frac{s-c}{s}}$$

IF $\Delta\nu > \pi$

$$\beta_{min} = -\beta_{min}$$

$$a_{min} = \frac{s}{2}$$

$$t_{min} = \sqrt{\frac{a_{min}^3}{\mu}} \{ \alpha_{min} - \beta_{min} + \sin(\beta_{min}) \}$$

$$\sin\left(\frac{\alpha_e}{2}\right) = \sqrt{\frac{s}{2a}}$$

$$\sin\left(\frac{\beta_e}{2}\right) = \sqrt{\frac{s-c}{2a}}$$

The $K(U)$ “ n ” coefficients should also be corrected as:

$$n = 0, 1, 2, \dots \text{IF } 2n \text{ even}$$

$$c_U = \frac{2(3n+1)(6n-1)}{9(4n-1)(4n+1)}$$

$$n = 0, 1, 2, \dots \text{IF } 2n+1 \text{ odd}$$

$$c_U = \frac{2(3n+2)(6n+1)}{9(4n+1)(4n+3)}$$

Page 542, 544, Eq 8-15, Eq 8-17: (3rd pg 541, 2nd pg 516 (513), 1st 490). In Eq 8-15, the “2” is not needed outside the summation. Inside the summation, there should be a $(2-\delta_k)$ term defined as “ k ”

was in Eq 8-22. In Eq 8-17, the $(2-\delta_k)$ term should be inside the integral. All three equations should use the δ_k parameter for consistency.

Page 550, Eq 8-27: (3rd pg 548, 2nd pg 524 (521), 1st 497) The final terms should be components of the position vector as follows:

$$a_I = \left\{ \frac{1}{r} \frac{\partial U}{\partial r} - \frac{r_K}{r^2 \sqrt{r_I^2 + r_J^2}} \frac{\partial U}{\partial \phi_{gc_{sat}}} \right\} r_I - \left\{ \frac{1}{r_I^2 + r_J^2} \frac{\partial U}{\partial \lambda_{sat}} \right\} r_J - \frac{\mu r_I}{r^3}$$

$$a_J = \left\{ \frac{1}{r} \frac{\partial U}{\partial r} - \frac{r_K}{r^2 \sqrt{r_I^2 + r_J^2}} \frac{\partial U}{\partial \phi_{gc_{sat}}} \right\} r_J + \left\{ \frac{1}{r_I^2 + r_J^2} \frac{\partial U}{\partial \lambda_{sat}} \right\} r_I - \frac{\mu r_J}{r^3}$$

$$a_K = \frac{1}{r} \frac{\partial U}{\partial r} r_K + \frac{\sqrt{r_I^2 + r_J^2}}{r^2} \frac{\partial U}{\partial \phi_{gc_{sat}}} - \frac{\mu r_K}{r^3}$$

Page 559, Next to last Eq: (3rd pg 557) The final Kp_4 and ap_4 terms should be divided by 6.

Page 575, Eq 8-35: The first equation denominators should be magnitudes, not vectors.

Page 589, Eq 8-50: (3rd pg 587, 2nd pg 550 (546), 1st 524) The F_{thrust} equation should have a “g” before “ I_{sp} ”.

Page 600, Last paragraph: (3rd pg 596, 2nd pg 559) “verification” should be “validation”.

Page 626, 2nd equation: (3rd pg 622, 2nd pg 584 (582), 1st 557) The Mean anomaly rate should have a “n” as the first term on the RHS.

Page 635, first equation: (3rd pg 631, 2nd pg 593 (591), 1st 566) The F_s term should have a $\text{SIN}(\nu)$ as well.

Page 636, first unnumbered equation: (3rd pg 632, 2nd pg 594 (592), 1st 567) The brackets should be as follows:

$$\frac{d\nu}{dt} = \frac{h}{r^2} + \frac{1}{eh} \left\{ p \cos(\nu) F_R - (p+r) \sin(\nu) F_S \right\}$$

Page 709, last line of SP radial rate term: (3rd pg 705) The term should be $(1+\text{ecos}(\nu))^2$.

Page 751, Center equation and text: (3rd pg 745, 2nd pg 694 (692), 1st 672) The text should be changed as follows

“For N unique sensor and observation type combinations,”
and

“Note that \mathbf{W} contains the weights (as appropriate) for each measurement. For example, if one sensor records right ascension-declination, and another records range azimuth and elevation, and each sensor produces 1 measurement, the \mathbf{W} matrix would be 5×5 . If each sensor took 6 measurements, the \mathbf{W} matrix would be 30×30 ! In practice, we accumulate measurements so the size of the \mathbf{W} matrix is much smaller. In the example above, the \mathbf{W} matrix would still be just 5×5 for all 6 measurements.”

The equation should read $w_i = \frac{1}{\sigma_A} = w_A \quad i = 1 \dots N$.

Page 802-803, last equation and top equation (803): (3rd pg 793, 2nd pg 743 (740)) The azimuth numerator and denominator are switched. Both terms in the numerator of the 3,3 matrix position should be squared.

Page 810, footnote equation: (3rd pg 801, 2nd pg 750) The Δt should be squared.

Page 865, first equation: (3rd pg 854, 2nd pg 788 (784), 1st 760) The semimajor axis should be “7178.1363” instead of “1.12532”.

Page 898-899, Eq 11-44: (3rd pg 887, 2nd pg 819 (815), 1st 791) The second negative sign from the left should be “+”. Top of 899, the Danielson reference should be from 2003.

Page 961, Ex 12-8: (3rd pg 44, 2nd pg 44 (44), 1st 126) The last sentence should be “came within about 340,000 km of Jupiter—certainly far enough out to avoid encountering the atmosphere. This is close to the actual value due to some approximations used in this example.”.

Page 972, second equation: (3rd pg 44, 2nd pg 44 (44), 1st 126) The first terms should be $1/2 - u^*$.